



Received: 25 September 2018  
Accepted: 06 December 2018  
First Published: 20 December 2018

\*Corresponding author: Maryam Ramezani, Department of Mathematics, University of Bojnord, Bojnord, Iran (ISLAMIC REPUBLIC OF)  
E-mail: [mar.ram.math@gmail.com](mailto:mar.ram.math@gmail.com)

Reviewing editor:  
Lishan Liu, Qufu Normal University, China

Additional information is available at the end of the article

## PURE MATHEMATICS | RESEARCH ARTICLE

# A new generalized contraction and its application in dynamic programming

M. Ramezani<sup>1\*</sup> and H. Ramezani<sup>2</sup>

**Abstract:** By using the idea of Pata [V. Pata, A fixed point theorem in metric spaces. *J. Fixed Point Theory Appl.* 10 (2011) 299–305.] we establish a new common fixed point theorem and as an application, we prove the existence and uniqueness of common solutions for a class of system of functional equations arising in dynamic programming.

**Subjects:** Applied Mathematics; Non-Linear Systems; Dynamical Systems

**Keywords:** dynamic programming; functional equations; contractive mapping; common fixed point

**MR Subject classifications:** 35B40; 35L70

### 1. Introduction

It is clear that fixed point theory is one of the powerful tools in solving nonlinear analysis problems such as integral and differential equations. The Banach contraction mapping principle is one of the pivotal results in fixed point theory and it has a board set of applications. Generalization of the above principle has been proved by various authors (see, for example, (Agarwal, Meehan, & O'Regan, 2001; Gordji & Ramezani, 2011; Harjani & Sadarangani, 2010)). In particular, recently, (Pata, 2011) improves the Banach principle. In this article, we present a common fixed point theorem by using the idea of Pata. As an application, the existence and uniqueness of common solution for a system of functional equations arising in dynamic programming are given.

### 2. Main results

Let  $(X, d)$  be a complete metric space. Selecting an arbitrary  $x_0 \in X$ . We denote

$$\|x\| = d(x, x_0)$$

### ABOUT THE AUTHORS

M. Ramezani has some papers in this field such as the following: 1. A generalization of Geraghty's fixed point theorem in partially ordered metric spaces and applications to ordinary differential equations, *Fixed Point Theory and Applications*, 2. Pata type fixed point theorems of multivalued operators in ordered metric spaces with applications to hyperbolic differential inclusions., *U.P.B. Sci. Bull., Series A.*, 3. Presic- Kannan- Rus fixed point theorem on partially ordered metric spaces, *Fixed Point Theory*.

H. Ramezani is a member of statistical research group in Payam noor University of Mashhad and he has a ISC published paper in Mathematics and Statistic by title: The estimation of a compound Poisson process by used wavelets.

### PUBLIC INTEREST STATEMENT

One of the powerful tools in solving nonlinear equations and dynamic programming problems is the Banach contraction principle and its generalizations. In this manuscript, we solve a dynamic programming by a generalization of Banach's fixed point theorem. Also, we give some examples to support our main results.



M. Ramezani

for all  $x \in X$ . We consider the function  $\psi : [0, 1] \rightarrow [0, \infty)$  such that  $\psi$  is an increasing function vanishing with continuity at zero. We will also consider the (vanishing) sequence depending on  $\alpha \geq 1$  by the following.

$$w_n(\alpha) = \left(\frac{\alpha}{n}\right)^n \sum_{k=1}^n \psi\left(\frac{\alpha}{k}\right).$$

Our first result is the following.

**Theorem 2.1.** Let  $f, g : X \rightarrow X$  and  $\Lambda \geq 0, \alpha \geq 1, \beta \in [0, \alpha]$  be fixed constants.

Suppose

$$d(fx, gy) \leq (1 - \varepsilon)M(x, y) + \Lambda \varepsilon^\alpha \psi(\varepsilon) [1 + \|x\| + \|y\|]^\beta \tag{2.1}$$

for all  $x, y \in X$  and  $\varepsilon \in (0, 1]$ , where

$$M(x, y) = \max \left\{ d(x, y), d(x, fx), d(y, gy), \frac{[d(x, gy) + d(y, fx)]}{2} \right\}.$$

Then  $f$  and  $g$  have a unique common fixed point.

*Proof.* Let  $x_0$  be an arbitrary element in  $X$ . We introduce the sequences

$$c_n = \|x_n\|, \quad fx_{2n} = x_{2n+1}, \quad gx_{2n+1} = x_{2n+2}$$

for all  $n \in \mathbb{N} \cup \{0\}$ . Note that

$$\begin{aligned} M(x_{2n}, x_{2n+1}) &= \max \left\{ d(x_{2n}, x_{2n+1}), d(x_{2n}, fx_{2n}), d(x_{2n+1}, gx_{2n+1}), \frac{d(x_{2n}, gx_{2n+1}) + d(x_{2n+1}, fx_{2n})}{2} \right\} \\ &= \max \left\{ d(x_{2n}, x_{2n+1}), d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2}), \frac{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2})}{2} \right\} \\ &\leq \max \left\{ d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2}), \frac{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2})}{2} \right\} \\ &= \max \{ d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2}) \}. \end{aligned}$$

If

$$x_{2n_0+1} = x_{2n_0+2}$$

for some  $n_0 \in \mathbb{N}$ , by using definition of sequence  $\{x_n\}$  we see that  $x_{2n_0+2} = gx_{2n_0+1}$  and  $x_{2n_0+1}$  is a fixed point of  $g$ . Also,

$$\begin{aligned} d(fx_{2n_0+1}, x_{2n_0+1}) &= d(fx_{2n_0+1}, gx_{2n_0+1}) \\ &\leq (1 - \varepsilon)d(x_{2n_0+1}, fx_{2n_0+1}) + \Lambda \varepsilon^\alpha \psi(\varepsilon) [1 + \|x_{2n_0+1}\| + \|x_{2n_0+1}\|]^\beta \end{aligned}$$

for all  $\varepsilon \in [0, 1]$ . So,

$$d(fx_{2n_0+1}, x_{2n_0+1}) \leq \Lambda \varepsilon^{\alpha-1} \psi(\varepsilon) [1 + 2 \|x_{2n_0+1}\|]^\beta$$

for all  $\varepsilon \in (0, 1]$ . If  $\varepsilon \rightarrow 0$  then  $x_{2n_0+1} = fx_{2n_0+1}$ . Hence  $x_{n_0+1}$  is a common fixed point of  $f$  and  $g$ . Now, we suppose that

$$x_{2n+1} \neq x_{2n+2}, \quad \forall n \in \mathbb{N}. \tag{2.2}$$

We divide the proof into several steps.

Step1:  $\{d(x_n, x_{n-1})\}$  is a nondecreasing sequence.

Let  $n$  be fixed, if

$$\max\{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2})\} = d(x_{2n+1}, x_{2n+2})$$

therefore,

$$d(x_{2n+1}, x_{2n+2}) \leq (1 - \varepsilon)d(x_{2n+1}, x_{2n+2}) + \Lambda\varepsilon^\alpha\psi(\varepsilon)[1 + \|x_{2n}\| + \|x_{2n+1}\|]^\beta$$

for all  $\varepsilon \in (0, 1]$ . Hence,

$$d(x_{2n+1}, x_{2n+2}) \leq \Lambda\varepsilon^{\alpha-1}\psi(\varepsilon)[1 + \|x_{2n}\| + \|x_{2n+1}\|]^\beta$$

for all  $\varepsilon \in (0, 1]$ . If  $\varepsilon \rightarrow 0$  then

$$d(x_{2n+1}, x_{2n+2}) = 0$$

that is a contradiction to (2.2). Therefore, we have

$$\max\{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2})\} = d(x_{2n}, x_{2n+1}).$$

Hence,

$$d(x_{2n+1}, x_{2n+2}) \leq (1 - \varepsilon)d(x_{2n}, x_{2n+1}) + \Lambda\varepsilon^\alpha\psi(\varepsilon)[1 + \|x_{2n}\| + \|x_{2n+1}\|]^\beta$$

for all  $\varepsilon \in (0, 1]$ . This show that

$$d(x_{2n+1}, x_{2n+2}) \leq d(x_{2n}, x_{2n+1}).$$

Thus, the sequence  $\{d(x_n, x_{n+1})\}$  is nonincreasing.

Step 2: The sequence  $c_n$  is bounded.

Fix  $n \in \mathbb{N}$ . By using Step 1 we have

$$d(x_{2n+1}, x_{2n+2}) \leq d(x_{2n}, x_{2n+1}) \leq \dots \leq d(x_0, x_1).$$

By the above and the triangle inequality we have

$$\begin{aligned} c_{2n+1} = d(x_{2n+1}, x_0) &\leq d(x_{2n+1}, x_{2n+2}) + d(x_{2n+2}, x_1) + d(x_1, x_0) = d(x_{2n+2}, x_1) + 2c_1 \\ &= d(gx_{2n+1}, fx_0) + 2c_1. \end{aligned}$$

Therefore, as  $\beta \leq \alpha$  we infer that

$$\begin{aligned} c_{2n+1} &\leq (1 - \varepsilon)d(x_{2n+1}, x_0) + \Lambda\varepsilon^\alpha\psi(\varepsilon)[1 + \|x_{2n+1}\| + \|x_0\|]^\beta + 2c_1 \\ &\leq (1 - \varepsilon)(c_{2n+1} + c_1) + \Lambda\varepsilon^\alpha\psi(\varepsilon)[1 + c_{2n+1}]^\beta + 2c_1 \\ &\leq (1 - \varepsilon)c_{2n+1} + a\varepsilon^\alpha\psi(\varepsilon)c_{2n+1}^\alpha + b \end{aligned}$$

for some  $a, b > 0$ . Accordingly,

$$\varepsilon c_{2n+1} \leq a\varepsilon^\alpha\psi(\varepsilon)c_{2n+1}^\alpha + b$$

If there is a subsequence  $c_{2n_k+1} \rightarrow \infty$ , the choice  $\varepsilon = \varepsilon_1 = (1 + b)/c_{2n_k+1}$  leads to the contradiction

$$1 \leq a(1 + b)^\alpha\psi(\varepsilon_1) \rightarrow 0.$$

Similarly, we have

$$c_{2n+2} \leq d(x_{2n+3}, x_2) + d(x_2, x_1) + 2c_1 \leq d(x_{2n+3}, x_2) + 3c_1$$

Therefore,

$$\begin{aligned} c_{2n+2} &\leq d(x_{2n+3}, x_2) + 3c_1 = d(fx_{2n+2}, x_1) + 3c_1 \\ &\leq (1 - \varepsilon)M(x_{2n+2}, x_1) + \Lambda\varepsilon^\alpha\psi(\varepsilon)[1 + \|x_{2n+2}\| + \|x_1\|]^\beta + 3c_1 \\ &\leq (1 - \varepsilon)(c_{2n+2} + 2c_1) + \Lambda\varepsilon^\alpha\psi(\varepsilon)[1 + c_{2n+2}]^\beta + 3c_1 \\ &\leq (1 - \varepsilon)c_{2n+2} + a'\varepsilon^\alpha\psi(\varepsilon)c_{2n+2}^\alpha + b' \end{aligned}$$

for some  $a', b' > 0$ . Accordingly,

$$\varepsilon c_{2n+2} \leq a'\varepsilon^\alpha\psi(\varepsilon)c_{2n+2}^\alpha + b'$$

If there is a subsequence  $c_{2n_k+2} \rightarrow \infty$ , the choice  $\varepsilon = \varepsilon_2 = (1 + b)/c_{2n_k+2}$  leads to the contradiction

$$1 \leq a'(1 + b)^\alpha\psi(\varepsilon_2) \rightarrow 0.$$

$$\text{Set } C = \sup_{n \in \mathbb{N}} \Lambda(1 + 2c_n)^\beta < \infty.$$

Step 3: The sequence  $\{x_n\}$  is Cauchy.

Since  $\{d(x_{2n}, x_{2n+1})\}$  is decreasing thus

$$d(x_{2n}, x_{2n+1}) \rightarrow r \geq 0$$

If  $r > 0$ , then

$$d(x_{2n}, x_{2n+1}) = d(gx_{2n-1}, fx_{2n}) \leq (1 - \varepsilon)M(x_{2n+1}, x_{2n}) + C\varepsilon^\alpha\psi(\varepsilon) \leq (1 - \varepsilon)d(x_{2n+1}, x_{2n}) + C\varepsilon^\alpha\psi(\varepsilon)$$

for all  $n \in \mathbb{N}$ , and  $\varepsilon \in (0, 1]$ . As  $n \rightarrow \infty$ , we have

$$r \leq (1 - \varepsilon)r + C\varepsilon^\alpha\psi(\varepsilon)$$

for all  $\varepsilon \in (0, 1]$ . So

$$r \leq C\varepsilon^{\alpha-1}\psi(\varepsilon)$$

for all  $\varepsilon \in (0, 1]$ . As  $\varepsilon \rightarrow 0$  we get  $r = 0$  and this is a contradiction, therefore  $r = 0$ .

Hence

$$\lim_{n \rightarrow \infty} d(x_{2n}, x_{2n+1}) = 0. \tag{2.3}$$

To show that  $\{x_n\}$  is Cauchy sequence, it is sufficient to show that the subsequence  $\{x_{2n}\}$  of  $\{x_n\}$  is a Cauchy sequence in view of (2.3). If  $\{x_{2n}\}$  is not Cauchy, there exist an  $\delta > 0$  and monotone increasing sequence of natural numbers  $\{2m_k\}$  and  $\{2n_k\}$  such that  $n_k > m_k$ ,

$$d(x_{2m_k}, x_{2n_k}) \geq \delta \quad \text{and} \quad d(x_{2m_k}, x_{2n_k-2}) < \delta. \tag{2.4}$$

From (2.4), we get

$$\begin{aligned} \delta &\leq d(x_{2m_k}, x_{2n_k}) \leq d(x_{2m_k}, x_{2n_k-2}) + d(x_{2n_k-2}, x_{2n_k-1}) + d(x_{2n_k-1}, x_{2n_k}) \\ &\leq \delta + d(x_{2n_k-2}, x_{2n_k-1}) + d(x_{2n_k-1}, x_{2n_k}). \end{aligned}$$

Letting  $k \rightarrow \infty$  and using (2.3) we have

$$\lim_{n \rightarrow \infty} d(x_{2m_k}, x_{2n_k}) = \delta. \tag{2.5}$$

Letting  $k \rightarrow \infty$  and using (2.3), (2.4) and (2.5), we get

$$|d(x_{2m_k}, x_{2n_k+1}) - d(x_{2m_k}, x_{2n_k})| \leq d(x_{2n_k}, x_{2n_k+1}).$$

Hence,

$$\lim_{n \rightarrow \infty} d(x_{2n_k+1}, x_{2m_k}) = \delta. \tag{2.6}$$

Letting  $k \rightarrow \infty$  and using (2.3) and (2.6), we have

$$|d(x_{2m_k-1}, x_{2n_k}) - d(x_{2m_k}, x_{2n_k})| \leq d(x_{2m_k}, x_{2m_k-1}),$$

which implies that

$$\lim d(x_{2n_k}, x_{2m_k-1}) = \delta. \tag{2.7}$$

Putting  $x = x_{2n_k}$  and  $y = x_{2m_k-1}$  in (2.1) we have

$$\begin{aligned} d(fx_{2n_k}, gx_{2m_k-1}) &\leq (1 - \varepsilon)M(x_{2n_k}, x_{2m_k-1}) + C\varepsilon^\alpha\psi(\varepsilon) \\ &= (1 - \varepsilon) \max\{d(x_{2n_k}, x_{2m_k-1}), d(x_{2n_k}, x_{2n_k+1}), d(x_{2m_k-1}, x_{2m_k}), \\ &\quad \frac{d(x_{2n_k}, x_{2m_k}) + d(x_{2m_k-1}, x_{2n_k+1})}{2}\} \\ &\leq (1 - \varepsilon) \max\{d(x_{2n_k}, x_{2m_k-1}), d(x_{2n_k}, x_{2n_k+1}), d(x_{2m_k-1}, x_{2m_k}), \\ &\quad \frac{d(x_{2n_k}, x_{2m_k}) + d(x_{2m_k-1}, x_{2m_k}) + d(x_{2m_k}, x_{2n_k+1})}{2}\} \end{aligned}$$

for all  $\varepsilon \in (0, 1]$ .

Letting  $k \rightarrow \infty$  and using (2.3), (2.4), (2.5), (2.6) and (2.7) we get

$$\delta \leq (1 - \varepsilon)\delta + C\varepsilon^\alpha\psi(\varepsilon)$$

for all  $\varepsilon \in (0, 1]$ . Thus

$$\delta \leq C\varepsilon^{\alpha-1}\psi(\varepsilon).$$

If  $\varepsilon \rightarrow 0$  then we have  $\delta = 0$  and it is a contradiction, therefore  $\{x_{2n}\}$  is a Cauchy sequence.

Step 4:  $fx_* = x_*$ .

Since  $X$  is complete, there exists  $x_* \in X$  such that  $x_n \rightarrow x_*$  as  $n \rightarrow \infty$ , so  $x_{2n} \rightarrow x_*$  and  $x_{2n+1} \rightarrow x_*$  so,

$$d(fx_*, gx_{2n+1}) \leq (1 - \varepsilon)M(x_*, x_{2n+1}) + C\varepsilon^\alpha\psi(\varepsilon)$$

for all  $\varepsilon \in [0, 1]$ .

$$M(x_*, x_{2n+1}) = \max\left\{d(x_*, x_{2n+1}), d(x_*, fx_*), d(x_{2n+1}, x_{2n+2}), \frac{d((x_*, x_{2n+2}) + d(x_{2n+1}, fx_*))}{2}\right\}.$$

As  $n \rightarrow \infty$  we have

$$d(fx_*, x_*) \leq (1 - \varepsilon)d(x_*, fx_*) + C\varepsilon^\alpha\psi(\varepsilon)$$

for all  $\varepsilon \in (0, 1]$ . So

$$d(x_*, fx_*) \leq C\varepsilon^{\alpha-1}\psi(\varepsilon)$$

for all  $\varepsilon \in (0, 1]$ . If  $\varepsilon \rightarrow 0$  then we get

$$d(x_*, fx_*) \rightarrow 0.$$

Hence  $fx_* = x_*$ .

Step 5:  $gx_* = x_*$ .

Now we show that  $x_*$  is a fixed point of  $g$  too,

$$0 < d(x_*, gx_*) = d(fx_*, gx_*) \leq (1 - \varepsilon) \max\{d(x_*, x_*), d(x_*, fx_*), d(x_*, gx_*), d(x_*, gx_*) + d(x_*, fx_*)/2\} + k\varepsilon\psi(\varepsilon)$$

where  $k > 0$ . So,

$$d(x_*, gx_*) \leq (1 - \varepsilon)d(x_*, gx_*) + k\varepsilon\psi(\varepsilon).$$

This implies that

$$d(x_*, gx_*) \leq k\psi(\varepsilon)$$

where  $\varepsilon \in (0, 1]$ . Since  $\psi$  is increasing and continuous at zero, then  $\psi(0) = 0$  and

$$d(x_*, gx_*) = 0.$$

Therefore  $x_* = gx_*$ .

Step 6: Uniqueness of  $x_*$ .

If there exists  $y_* \in X$  that  $y_* = fy_* = gy_*$ , then

$$d(x_*, y_*) = d(fx_*, gy_*) \leq (1 - \varepsilon)d(x_*, gy_*) + k\varepsilon\psi(\varepsilon) = (1 - \varepsilon)d(x_*, y_*) + k\varepsilon\psi(\varepsilon).$$

Setting  $\varepsilon = 0$ ,

$$d(x_*, y_*) = 0$$

and so  $y_* = x_*$

**Theorem 2.2.** Let  $\rho : [0, \infty) \rightarrow [0, \infty)$  be a continuous function satisfying the inequality  $\rho(r) < r$  for every  $r > 0$ , suppose that for every  $x, y$  with,  $x \neq y$

$$d(fx, gy) \leq \rho(M(x, y)) \tag{2.8}$$

where

$$M(x, y) = \max\left\{d(x, y), d(x, fx), d(y, gy), \frac{d(x, gy) + d(y, fx)}{2}\right\}.$$

Then  $f$  and  $g$  have a unique common fixed point  $x_*$  and  $d(x_*, x_n) \rightarrow 0$ , where  $\{x_n\}$  is the sequence is defined in Theorem 2.1.

*Proof.* We introduce the intreat sequences

$$fx_{2n} = x_{2n+1}, gx_{2n+1} = x_{2n+2}.$$

Note that

$$\begin{aligned} M(x_{2n}, x_{2n+1}) &= \max\left\{d(x_{2n}, x_{2n+1}), d(x_{2n}, fx_{2n}), d(x_{2n+1}, gx_{2n+1}), \frac{d(x_{2n}, gx_{2n+1}) + d(x_{2n+1}, fx_{2n})}{2}\right\} \\ &= \max\left\{d(x_{2n}, x_{2n+1}), d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2}), \frac{d(x_{2n}, x_{2n+1}) + d(x_{2n+1}, x_{2n+2})}{2}\right\} \\ &\leq \max\left\{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2}), \frac{d(x_{2n}, x_{2n+1}) + d(x_{2n+1}, x_{2n+2})}{2}\right\} \\ &= \max\{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2}).\} \end{aligned}$$

Let  $n \in \mathbb{N}$  be fixed, if

$$\max\{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2})\} = d(x_{2n+1}, x_{2n+2})$$

Therefore,

$$d(x_{2n+1}, x_{2n+2}) = d(fx_{2n}, gx_{2n+1}) \leq (d(x_{2n+1}, x_{2n+2})) < d(x_{2n+1}, x_{2n+2}).$$

That is a contradiction. Therefore we have

$$\max\{d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2})\} = d(x_{2n}, x_{2n+1}).$$

So,

$$d(x_{2n+1}, x_{2n+2}) \leq d(x_{2n}, x_{2n+1}).$$

Hence,  $\{d(x_{2n}, x_{2n+1})\}$  is a decreasing sequence that converges monotonically to some  $r \geq 0$ .

If  $r > 0$ , then

$$d(x_{2n}, x_{2n+1}) = d(gx_{2n-1}, fx_{2n}) \leq (d(x_{2n-1}, x_{2n})).$$

As  $n \rightarrow \infty$ , we have  $r \leq \rho(r) < r$  and this is a contradiction, therefore  $r = 0$ . Hence

$$\lim d(x_{2n}, x_{2n+1}) = 0 \tag{2.9}$$

To show that  $\{x_n\}$  is Cauchy sequence, it is sufficient to show that the subsequence  $\{x_{2n}\}$  of  $\{x_n\}$  is Cauchy sequence in view of (2.9). If  $\{x_{2n}\}$  is not Cauchy there exist an  $\delta > 0$  and natural numbers  $n_k$  and  $m_k$  such that  $n_k > m_k$ , and

$$d(x_{2m_k}, x_{2n_k}) \geq \delta \quad \text{and} \quad d(x_{2m_k}, x_{2n_k-2}) < \delta. \tag{2.10}$$

From (2.10),

$$\begin{aligned} \delta \leq d(x_{2m_k}, x_{2n_k}) &\leq d(x_{2m_k}, x_{2n_k-2}) + d(x_{2n_k-2}, x_{2n_k-1}) + d(x_{2n_k-1}, x_{2n_k}) \\ &\leq \delta + d(x_{2n_k-2}, x_{2n_k-1}) + d(x_{2n_k-1}, x_{2n_k}). \end{aligned}$$

Letting  $k \rightarrow \infty$  and using (2.9) we have

$$\lim_{k \rightarrow \infty} d(x_{2m_k}, x_{2n_k}) = \delta. \tag{2.11}$$

Letting  $k \rightarrow \infty$  and using (2.9) and (2.10)

$$|d(x_{2m_k}, x_{2n_k+1}) - d(x_{2m_k}, x_{2n_k})| \leq d(x_{2n_k}, x_{2n_k-1}).$$

Hence,

$$\lim_{k \rightarrow \infty} d(x_{2n_k+1}, x_{2m_k}) = \delta. \tag{2.12}$$

Letting  $k \rightarrow \infty$  and using (2.9) and (2.10)

$$|d(x_{2m_k-1}, x_{2n_k}) - d(x_{2m_k}, x_{2n_k})| \leq d(x_{2m_k}, x_{2m_k-1}).$$

Hence,

$$\lim_{k \rightarrow \infty} d(x_{2n_k}, x_{2m_k-1}) = \delta \tag{2.13}$$

Putting  $x = x_{2n_k}$  and  $y = x_{2m_k-1}$  in (2.8) we have

$$\begin{aligned} d(fx_{2n_k}, gx_{2m_k-1}) &\leq \rho(m(x_{2n_k}, x_{2m_k-1})) \\ &\leq \rho(\max\{d(x_{2n_k}, x_{2m_k-1}), d(x_{2n_k}, x_{2n_k+1}), d(x_{2m_k-1}, x_{2m_k}) \\ &\quad \frac{d(x_{2n_k}, x_{2m_k}) + d(x_{2m_k-1}, x_{2n_k+1})}{2}\}) \\ &\leq \rho(\max\{d(x_{2n_k}, x_{2m_k-1}), d(x_{2n_k}, x_{2n_k+1}), d(x_{2m_k-1}, x_{2m_k}) \\ &\quad \frac{d(x_{2n_k}, x_{2m_k}) + d(x_{2m_k-1}, x_{2n_k}) + d(x_{2n_k}, x_{2n_k+1})}{2}\}). \end{aligned}$$

Letting  $k \rightarrow \infty$  and using (2.9), (2.10), (2.11), (2.12) and (2.13) we get

$$\delta \leq \rho(\delta) < \delta$$

and this is a contradiction. Hence,  $\{x_{2n}\}$  is a Cauchy sequence. Since  $X$  is complete, there exists  $x_* \in X$  such that  $x_n \rightarrow x_*$  as  $n \rightarrow \infty$ . Hence,  $x_{2n} \rightarrow x_*$  and  $x_{2n+1} \rightarrow x_*$ . Assume that  $fx_* \neq x_*$ ,

$$d(fx_*, gx_{2n+1}) \leq \rho(m(x_*, x_{2n+1}))$$

as  $n \rightarrow \infty$  we have

$$d(fx_*, x_*) \leq \rho(d(x_*, fx_*)) < d(x_*, fx_*)$$

and this is a contradiction. Suppose that  $gx_* \neq x_*$ , therefore

$$\begin{aligned} d(x_*, gx_*) &= d(fx_*, gx_*) \leq \rho(m(x_*, x_*)) \\ &= \rho(\max(d(x_*, x_*), d(x_*, fx_*), d(x_*, gx_*), \frac{d(x_*, gx_*) + d(x_*, fx_*)}{2})) = \rho(d(x_*, gx_*)) < d(x_*, gx_*) \end{aligned}$$

that is a contradiction, therefore  $x_*$  is a fixed point of  $g$  too.

If there exists  $y_* \in X$  that  $y_* \neq x_*$  and

$$y_* = fy_* = gy_*,$$

then,

$$\begin{aligned} d(x_*, y_*) &= d(fx_*, gy_*) \leq \rho(M(x_*, y_*)) \leq \rho(\max(d(x_*, y_*), d(x_*, x_*), d(y_*, y_*), \frac{d(x_*, y_*) + d(y_*, x_*)}{2})) \\ &= \rho(d(x_*, y_*)) < d(x_*, y_*), \end{aligned}$$

and it is a contradiction which completes the proof.

**Example 2.3.** Let  $X = [1, \infty)$  with Euclidean metric and  $f, g : X \rightarrow X$  be two mappings by defined  $f(x) = g(x) = x - 2x^{\frac{1}{2}} + 4x^{\frac{1}{4}} - 2$ . It is clear that  $x^* = 1$  is a unique common fixed point of  $f$  and  $g$ . For all  $x, y \in [1, \infty)$  with  $y > x$  we have

$$fy - gx = (y - x) - 2[y^{\frac{1}{2}} - x^{\frac{1}{2}}] + 4[y^{\frac{1}{4}} - x^{\frac{1}{4}}] = (y - x) - F(x, y).$$

where  $F(x, y) = 2[y^{\frac{1}{2}} - x^{\frac{1}{2}}] - 4[y^{\frac{1}{4}} - x^{\frac{1}{4}}]$ . For every  $\varepsilon \in (0, 1]$  standard calculations show that

$$-\varepsilon(y - x) + \varepsilon^2(2x + (y - x))^{\frac{3}{2}} + F(x, y) \geq 0.$$

Hence,

$$|fy - gx| = (y - x) - F(x, y) \leq (1 - \varepsilon)(y - x) + \varepsilon^2(2x + (y - x))^{\frac{3}{2}} \leq (1 - \varepsilon)M(x, y) + \varepsilon^2(2x + (y - x))^{\frac{3}{2}}$$

by putting  $\Lambda = \alpha = \beta = 1, x_0 = 1$  and  $\psi(r) = r$  we can see all assumptions of Theorem 2.1 hold. Therefore, the existence and uniqueness of common fixed point of  $f$  and  $g$  implies from Theorem 2.1.

**Proposition 2.4.** If  $X$  is a bounded space, Theorem 2.1 and Theorem 2.2 imply each other.

*Proof.* Suppose for simplicity that  $\text{diam}(X) \leq 1$ . Then for all  $x, y \in X, \|x\| \leq 1, \|y\| \leq 1$  and the inequality (2.1) reads



$$d(fx, gy) \leq (1 - \varepsilon)M(x, y) + \Lambda\varepsilon^\alpha\psi(\varepsilon). \tag{2.14}$$

We first prove the implication (2.14)  $\Rightarrow$  (2.8). Define  $\varphi(r) := \psi^{-1}(\nu r)$  with  $\nu > 0$  suitably small and the function  $\rho$  by

$$\rho(r) = r - r\varphi(r)[1 - \nu\Lambda[\varphi(r)]^{\alpha-1}].$$

It is obvious that  $\rho(r) < r$  for all  $r > 0$ , also, the continuity of  $\psi$  implies the continuity of  $\rho$ . Since  $\psi$  is defined on  $[0, 1]$ , then we can choose  $\varepsilon = \varphi(M(x, y))$  in (2.14). The inequality of (2.14) and definition of  $\rho$  follows that

$$\begin{aligned} d(fx, gy) &\leq (1 - \varepsilon)M(x, y) + \Lambda\varepsilon^\alpha\psi(\varepsilon) = [1 - \varphi(M(x, y))]M(x, y) + \Lambda\nu M(x, y)\varphi(M(x, y))^\alpha \\ &= [1 - \varphi(M(x, y))](\rho(M(x, y)) + M(x, y)\varphi(M(x, y))[1 - \nu\Lambda[\varphi(M(x, y))]^{\alpha-1}]) \\ &\quad + \Lambda\nu M(x, y)\varphi(M(x, y))^\alpha. \end{aligned}$$

By algebraic calculations we conclude that  $d(fx, gy) \leq \rho(M(x, y))$  and so the inequality (2.8) is hold.

Conversely, let (2.8) holds. Since  $\rho$  is continuous and  $\rho(r) < r$  on  $(0, 1]$ , we can easily construct a strictly increasing continuous function  $\mu$  such that  $\mu(0) = 0$  and

$$\mu(r) \leq 1 - \frac{\rho(r)}{r} \quad \forall r \in (0, 1]$$

Let  $x, y \in X$  with  $m(x, y) = r \in (0, 1]$  be given. By virtue of (2.8),

$$d(fx, gy) \leq \rho(r) \leq r - r\mu(r) < r$$

If  $\mu(r) \geq \varepsilon$ , we readily obtain

$$d(fx, gy) \leq (1 - \varepsilon)r$$

Whereas if  $\mu(r) < \varepsilon$ , we get

$$d(fx, gy) < (1 - \varepsilon)r + \varepsilon r < (1 - \varepsilon)r + \varepsilon\mu^{-1}(\varepsilon)$$

Collecting the two inequalities (2.14) follows for  $\Lambda = 1$  and  $\psi(\varepsilon) = \mu^{-1}(\varepsilon)$  if  $\varepsilon \leq \mu(1)$ ,  $\psi(\varepsilon) = 1$  otherwise.

**Corollary 2.5.** Let  $(X, d)$  be a complete metric space. Selecting an arbitrary  $x_0 \in X$ . We denote

$$\|x\| = d(x, x_0) \quad \forall x \in X$$

Let  $f, g : X \rightarrow X$  and  $\Lambda \geq 0, \alpha \geq 1, \beta \in [0, \alpha]$  be fixed constants. Suppose

$$d(fx, gy) \leq (1 - \varepsilon)M(x, y) + \Lambda\varepsilon^\alpha\psi(\varepsilon)[1 + \|x\| + \|y\|]^\beta$$

for all  $x, y \in X$  and  $\varepsilon \in [0, 1]$ , where

$$M(x, y) = \max\{d(x, y), [d(x, fx) + d(y, gy)]/2, [d(x, gy) + d(y, fx)]/2\}.$$

Then  $f$  and  $g$  have a unique common fixed point.

*Proof.* Since  $[d(x, fx) + d(y, gy)]/2$  is the average of  $d(x, fx)$  and  $d(y, gy)$ , then

$$[d(x, fx) + d(y, gy)]/2 \leq d(x, fx) \quad \text{or} \quad d(y, gy).$$

The result is seen by Theorem 2.1.

### 3. Application

Let  $X$  and  $Y$  be Banach spaces,  $S \subseteq X$  be the state space,  $D \subseteq Y$  be the decision space (for more details, the reader can see (Harjani & Sadarangani, 2010; Li, Fu, Liu, & Kang, 2008)), and  $i_x$  be the

identity mapping on  $X$ .  $B(S)$  denotes the set of all bounded real-valued functions on  $S$  and  $d(f, g) = \sup\{|f(x) - g(x)| : x \in S\}$ . It is clear that  $(B(S), d)$  is a complete metric space.

In this section we study the existence and uniqueness of a common solution of the following system of functional equations arising in dynamic programming:

$$f_i(x) = \sup_{y \in D} \{u(x, y) + H_i(x, y, f_i(T(x, y)))\}, \quad \forall x \in S, i \in \{1, 2\}, \tag{3.1}$$

where  $u : S \times D \rightarrow \mathbb{R}$ ,  $T : S \times D \rightarrow S$ , and  $H_i : S \times D \times \mathbb{R} \rightarrow \mathbb{R}$  for  $i \in \{1, 2\}$

**Theorem 3.1.** *Suppose that the following conditions are satisfied:*

- (a1)  $u$  and  $H_i$  are bounded for  $i \in \{1, 2\}$ ;
- (a2) There exist two mappings  $A_1$  and  $A_2$  defined by

$$A_i g_i(x) = \sup_{y \in D} \{u(x, y) + H_i(x, y, g_i(T(x, y)))\}, \quad \forall x \in S, g_i \in B(S), i \in \{1, 2\},$$

satisfying

$$|H_1(x, y, g(t)) - H_2(x, y, h(t))| \leq (1 - \varepsilon) \max\{d(g, h), d(g, A_1 g), d(h, A_2 h), \frac{1}{2}[d(g, A_2 h) + d(h, A_1 g)]\} + \Lambda \varepsilon^\alpha \psi(\varepsilon)[1 + \|g\| + \|h\|]^\beta$$

for all  $(x, y) \in S \times D$ ,  $g, h \in B(S)$ ,  $t \in S$  where  $\varepsilon \in (0, 1]$ ,  $\Lambda, \psi$  are as in Theorem 2.1;

(a3)  $A_1(B(S)) \subseteq B(S)$ ,  $A_2(B(S)) \subseteq B(S)$

(a4) There exists some  $A_i \in \{A_1, A_2\}$  such that for any sequence  $\{h_n\}_{n \geq 1} \subseteq B(S)$  and  $h \in B(S)$ ,

$$\lim_{n \rightarrow \infty} \sup_{x \in S} |h_n(x) - h(x)| = 0 \Rightarrow \lim_{n \rightarrow \infty} \sup_{x \in S} |A_i h_n(x) - A_i h(x)| = 0,$$

Then the system of functional Equations (3.1) has a unique common solution in  $B(S)$ .

*Proof.* It follows from (a1) to (a4) that  $A_1$  and  $A_2$  is continuous self-mappings of  $B(S)$ . Let  $\delta > 0$  be given. For any  $g, h \in B(S)$ ,  $x \in S$ , there exist  $y, z \in D$  such that

$$A_1 g(x) < u(x, y) + H_1(x, y, g(T(x, y))) + \delta \tag{3.2}$$

$$A_2 h(x) < u(x, z) + H_2(x, z, h(T(x, y))) + \delta \tag{3.3}$$

Not that

$$A_1 g(x) \geq u(x, z) + H_1(x, z, g(T(x, z))) \tag{3.4}$$

$$A_2 h(x) \geq u(x, y) + H_2(x, z, h(T(x, y))) \tag{3.5}$$

It follows from (3.2), (3.5) and (a2) that

$$\begin{aligned} A_1 g(x) - A_2 h(x) &< H_1(x, y, g(T(x, y))) - H_2(x, y, h(T(x, y))) + \delta \\ &\leq (1 - \varepsilon) \max\{d(g, h), d(g, A_1 g), d(h, A_2 h), \frac{1}{2}[d(g, A_2 h) + d(h, A_1 g)]\} \\ &\quad + \Lambda \varepsilon^\alpha \psi(\varepsilon)[1 + \|g\| + \|h\|]^\beta + \delta. \end{aligned} \tag{3.6}$$

In view of (3.3), (3.4) and (a2) that

$$\begin{aligned} A_1 g(x) - A_2 h(x) &> H_1(x, z, g(T(x, z))) - H_2(x, z, h(T(x, z))) - \delta \\ &\geq -(1 - \varepsilon) \max\{d(g, h), d(g, A_1 g), d(h, A_2 h), \frac{1}{2}[d(g, A_2 h) - d(h, A_1 g)]\} \\ &\quad + \Lambda \varepsilon^\alpha \psi(\varepsilon)[1 + \|g\| + \|h\|]^\beta - \delta \end{aligned} \tag{3.7}$$

(3.6) and (3.7) ensure that

$$\begin{aligned} d(A_1g(x) - A_2h(x)) &= \sup_{x \in S} |A_1g(x) - A_2h(x)| \\ &\leq (1 - \epsilon) \max\{d(g, h), d(g, A_1g), d(h, A_2h), \frac{1}{2}[d(g, A_2h) + d(h, A_1g)]\} \\ &\quad + \Lambda \epsilon^\alpha \psi(\epsilon) [1 + \|g\| + \|h\|]^\beta + \delta \end{aligned} \quad (3.8)$$

It follows from (3.8) that Theorem 2.1 implies that  $A_1$  and  $A_2$  have a unique common fixed point  $\nu \in B(S)$ , that  $\nu(x)$  is a unique common solution of the system of functional Equations (3.1).

#### Funding

The authors received no direct funding for this research.

#### Author details

M. Ramezani<sup>1</sup>

E-mail: [mar.ram.math@gmail.com](mailto:mar.ram.math@gmail.com)

H. Ramezani<sup>2</sup>

E-mail: [hosseinramezani40@yahoo.com](mailto:hosseinramezani40@yahoo.com)

<sup>1</sup> Department of Mathematics, University of Bojnord, Bojnord, Iran.

<sup>2</sup> Department of Statistics, Payame Noor University of Mashhad, Mashhad, Iran.

#### Citation information

Cite this article as: A new generalized contraction and its application in dynamic programming, M. Ramezani & H. Ramezani, *Cogent Mathematics* (2018), 5: 1559456.

#### References

- Agarwal, P., Meehan, M., & O'Regan, D. (2001). *Fixed point theory and applications*. Cambridge: Cambridge University Press.
- Gordji, M. E., & Ramezani, M. (2011). A generalization of Mizoguchi and Takahashi's theorem for single-valued mappings in partially ordered metric spaces. *Nonlinear Analysis*, 74(1), 4544–4549. doi:10.1016/j.na.2011.04.020
- Harjani, J., & Sadarangani, K. (2010). Generalized contractions in partially ordered metric spaces and applications to ordinary differential equations. *Nonlinear Analysis: Theory, Methods & Applications*, 72, 1188–1197. doi:10.1016/j.na.2009.08.003
- Li, J., Fu, M., Liu, Z., & Kang, M. (2008). Common fixed point theorem and its application in dynamic programming. *Applied Mathematical Sciences*, 2, 829–842.
- Pata, V. (2011). A fixed point theorem in metric spaces. *Journal of Fixed Point Theory and Applications*, 10, 299–305. doi:10.1007/s11784-011-0060-1



© 2019 The Author(s). This open access article is distributed under a Creative Commons Attribution (CC-BY) 4.0 license.

You are free to:

Share — copy and redistribute the material in any medium or format.

Adapt — remix, transform, and build upon the material for any purpose, even commercially.

The licensor cannot revoke these freedoms as long as you follow the license terms.

Under the following terms:

Attribution — You must give appropriate credit, provide a link to the license, and indicate if changes were made.

You may do so in any reasonable manner, but not in any way that suggests the licensor endorses you or your use.

No additional restrictions

You may not apply legal terms or technological measures that legally restrict others from doing anything the license permits.



**Cogent Mathematics (ISSN: 2331-1835) is published by Cogent OA, part of Taylor & Francis Group.**

**Publishing with Cogent OA ensures:**

- Immediate, universal access to your article on publication
- High visibility and discoverability via the Cogent OA website as well as Taylor & Francis Online
- Download and citation statistics for your article
- Rapid online publication
- Input from, and dialog with, expert editors and editorial boards
- Retention of full copyright of your article
- Guaranteed legacy preservation of your article
- Discounts and waivers for authors in developing regions

**Submit your manuscript to a Cogent OA journal at [www.CogentOA.com](http://www.CogentOA.com)**

